# Improving procedural tree generation

#### Donovan Foster - Richard Pieterse - Ryan Mazzolini Supervisor: Prof. James Gain









#### Project Summary

- Our project builds on an existing system that procedurally generates trees using parameterised L-systems
- The aim is to increase realism of the generated models
- The end result of the improved system will be a tree model that has foliage, more natural branch joints and is textured with a user specified sample.



#### Tree Draw

- Developed as an Honours project last year by Matthew Black, Mark Donaher and Neil Goldberg
- Users sketch the outline of the tree they would like to generate
- An L-system interpreter converts the sketch into an L-system
- L-system is then used to generate a 3D model
- Can generate multiple similar trees from one sketch



#### Tree Draw

Limitations:

- The branches are modelled as a set of generalised cylinders.
- It is textured by tiling a single sample
- The current system does not generate any leaves



#### Problem Statement

Improve the realism procedurally generated trees through the addition of:

- Surface subdivision of the trunk and branches
- Texture synthesis of bark
- Procedural leaf distribution based on user sketches





#### **Proposal Overview**

#### Research areas:

- Subdivision surfaces Richard Pieterse
- Texture synthesis Ryan Mazzolini
- Procedural leaf distribution Donovan Foster
- System and work allocation
- Evaluation plan
- Timeline

#### Subdivision Surfaces





(d)

### Subdivision surfaces Research Question

#### Can subdivision surfaces be used model more natural curves where branches meet?





Unnaturally sharp joins produced by Tree Draw

Natural curve of a real tree

### Subdivision surfaces An example



Control mesh subdivided using the Catmull-Clarke method

### Subdivision surfaces An example



### Subdivision surfaces Quasi-Interpolation

- Users to specify nets of parametric curves
- Subdivision surface conforms to the curves
- These curves could be banded around the base of branches





#### Texture Synthesis



### Texture Synthesis Research Question

Can the realism for bark on tree models be improved through the use of texture synthesis?

- The texture should be *accurate* according to user specification
- Visual artifacts should be *minimised* eg. artifacts across branch joints etc.
- Performance should be *transparent* or at minimal cost to the user

#### **Texture Synthesis**

The existing system uses a single tileable texture specified by the system for the bark.

This produces:

- Artifacts across the joining areas of the branches
- Repeating patterns
- Smooth shading emphasises that the image is wrapped over a cylinder



### Texture Synthesis Background

There are two existing texture synthesis methods.

Texture synthesis through procedural generation and through example-based methods.

Three example-based methods:

- Pixel-based
- Patch-based
- Tile-based







### Texture Synthesis Proposed Solution

The proposed solutions are example-based techniques.

The first is a *pixel-based* approach proposed by Ashikhmin specific for natural textures. (2001)

A possible alternative is the patch and pixel-based hybrid method by Kwatra et al. (2005)



### Texture Synthesis Proposed Solution Extensions

Possible extensions to the texture synthesis part of this project include:

- Fracture simulation over the barks surface
- Bump-mapping
- Texture placement on arbitrary manifold surfaces



#### **Procedural Leaf Distribution**



### Procedural Leaf Distribution Research Question

Can the realism of a procedural tree be improved with the addition of leaves?



Can leaves be added to a procedural tree using a sketch-based interface?

From TreeDraw and Sketch-based tree modeling using Markov random field.(Xuejin et al. 2008)

### Procedural Leaf Distribution Background

Phylotactic Distribution
Placed based on generation rules



From: The sketch I-system: Global control of tree modeling using free-form strokes (Ijiri et all 2006)

#### Procedural Leaf Distribution Background

- Global-to-local
  - 3D Bounding volumes for leaves



From: The Use of Positional Information in the Modeling of Plants (Prusinkiewicz et al. 2001)

#### Procedural Leaf Distribution Background

- Sketch-and-Spray
  - $\circ$  3D spraypainting of leaves



A Sketch-and-Spray Interface for Modeling Trees(Shukri et al. 2007)

- Sketching Interface
- Overlays tree sketching interface
- User-specified parameters
  - o Placement
  - Leaf density
  - Colour
  - Leaf type (Texture)
- Will try several solutions
  - Parameter adjustment
  - Sketching interface
    - Bounding volumes

Current Solution





From TreeDraw

Adding leaves to branches



From TreeDraw and Sketch-based tree modeling using Markov random field.(Xuejin et al. 2008)

- Bounding Branches
  - Sketch volumes



From Sketch-based tree modeling using Markov random field.(Xuejin et al. 2008)

#### Procedural Leaf Distribution Possible Extension

Painting foliage



From Sketch-based tree modeling using Markov random field.(Xuejin et al. 2008)

#### Development Plan

#### System and Work Allocation



## Evaluation Plan Quantitative

Numerical measurements of:

- Performance
  - Execution time will be recorded of each component as well as and the entire system and compared to the existing system
- Stability
  - The number of faults that occur during user testing will be numerically recorded

# Evaluation Plan Qualitative

#### User Testing

- Usability
  - Users asked to recreate a sketch
- Accuracy
  - $_{\odot}$   $\,$  Users asked to recreate a 3D Tree from the system
- Realism
  - Generated trees will be placed into real environments and shown to who will be users will be asked to identify the real tree

#### Users will be asked to comment on their

#### Timeline

- 1. Internship (4 weeks)
- 2. Design (1 week)
- 3. Initial implementation (3 weeks)
- 4. Initial user testing (1 week)
- 5. Implementation (4 weeks)
- 6. Final user testing (1 week)
- 7. Final project integration (1 week)
- 8. Final prototype and testing (2 weeks)
- 9. Write up (4 weeks)
- 10. Final due date (28th September)



#### Questions?



## Questions?







#### Risks

- Scoping
- Difficulties understanding the existing system
- Flaws or faults in the existing system
- Ethical clearance denied
- Member becomes unavailable
- Data loss
- Irregular project meetings and updates
- Internship Issues

## Evaluation Plan Qualitative

Who are the users for user testing?

- Feasibility demonstration
  - $\circ$   $\,$  Project supervisor and other lecturers
- Initial user testing
  - Small group of students
  - industry members(Triggerfish)
- Final user testing
  - Large group of students

Our project supervisor will be asked for feedback on a weekly basis throughout development

#### Realism vs. Interactivity

- Interactivity: time taken for the tree to be generated and rendered
- The interactivity of the current system is 30 seconds
- The improved realism from our sections will likely increase the generations and reder time
- Users must be able to prioritise between realism and waiting time
- The proposed components must all have variable

### Evaluation Plan Metrics

- Usability: ease of use and learnability
- Accuracy: resemblance to what the user intended
- *Realism*: resemblance to a real tree
- *Performance*: response time for task competion
- *Stability*: the robustness of the system